

Line Tracer Robot Project Report

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1. Name of Institution A project report on Line follower robot SUBMITTED BY: PRIYA HADA B.TECH ECE (SECTION –B) VTH SEM 1 2. CONTENTS Name of Institution OBJECTIVE WHAT IS A LINE TRACER? ITS COMPONENTS • LM324 • IC7805 • MICROPROCESSOR • L293D BLOCK DIAGRAM WORKING ECONOMIC IMPORTANCE 2 3.

Line follower robot - SlideShare

Line follower is an autonomous robot which follows either black line in white area or white line in black area. Robot must be able to detect particular line and keep following it. For special situations such as cross overs where robot can have more than one path which can be followed, predefined path must be followed by the robot.

Line Follower Robot - Electronic Projects, Electrical ...

A Line Follower Robot, as the name suggests, is an automated guided vehicle, which follow a visual line embedded on the floor or ceiling. Usually, the visual line is the path in which the line follower robot goes and it will be a black line on a white surface but the other way (white line on a black surface) is also possible.

Arduino Line Follower Robot - Electronics Hub

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About this project The purpose of this project is to build a Line Follower Robot with PID control. We will also use an Android device to easily setup the main control parameters for better and fast tuning. This project is the first of a 2 parts more complex project where my intention is to explore the potentiality of Line Follower Robots.

Line Follower Robot - PID Control - Arduino Project Hub

Pick and place Line following robot report 1. LINE FOLLOWING PICK AND PLACE ROBOT A Project submitted in partial fulfillment of the requirements for the award of the degree of B.Tech in ELECTRONICS AND INSTRUMENTATION By YASH KUMAR YADAV (1009032059) VINOD KUMAR (1009032058) PRADEEP KUMAR (1009032037) ELECTRONICS AND INSTRUMENTATION IEC COLLEGE OF ENGINEERING & TECHNOLOGY GREATER NOIDA MAY 2014 1

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Line Tracer Robot Project Report - ModApkTown

The line follower robot presented here is designed to follow a black line on a white background. It has a pair of sensors (LED / LDR) and works on a simple "align robot on the center of the line algorithm". Actually you does not need a microcontroller for implementing such a simple robot.